

# Estimation of the lunar reflectance by ground-based observation using a tunable liquid-crystal filter telescope

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Lunar reflectance data are useful not only for lithological identification of the lunar surface but also for radiometric calibration and determination of exposure time for optical sensors of lunar probes. To gain data on lunar reflectance, we acquired multi-band images (five bands: 650, 750, 900, 950, and 1000 nm) of the lunar surface and those of some standard stars using a liquid-crystal tunable filter (LCTF) telescope located on the peak of Mt. Haleakala (Hawaii, USA). The data obtained indicate that the reflectance data of Clementine UV/VIS is too high and that the correction factor is  $0.59 \pm 0.06$  at 950 nm. Our new reflectance data are available to the public at the web site of one of authors (K.S.). We report here our method of deriving the lunar reflectance images from the ground-based observation with a hyperspectral telescope for the users of our reflectance data. The results suggest that ground-based observation is more suitable for the radiometric calibration of the sensor of a lunar probe than laboratory data.

**Key words:** Clementine, the Moon, hyper-spectral telescope, reflectance, SELENE.

## 1. Introduction

The Japanese lunar probe SELENE (KAGUYA) was launched on 14 September 2007 by JAXA (Japan Aerospace Exploration Agency). As co-investigators of the SELENE project, some of the authors of this article are observing the global mineral distribution of the lunar surface in nine band images with the Lunar Imager and Spectrometer (LISM) onboard SELENE. The lunar reflectance is an important factor for determining the exposure-time-setting plan of these sensors. McEwen (1996) derived the global visible reflectance model with the images of Clementine Spacecraft launched in 1994. The UV/VIS data set and its calibration method are freely available to the public, therefore many studies have been carried out based on these data. Shkuratov *et al.* (2001), however, concluded that the albedo of the lunar surface determined by Clementine turns out to be a factor of 2 or 3 higher than that inferred from ground-based measurements due to the photometrically non-representative calibration standards. By comparing Clementine observations with prior ground-based observations on 15 sites on the Moon, Hillier *et al.* (1999) determined a good absolute calibration of the Clementine UV/VIS camera. A correction factor of 0.532 was determined as the conversion factor for converting the web site reflectances to absolute values. The latest photometric models were reported by the Robotic Lunar Observatory (ROLO) project (Kieffer and Stone, 2005). This model

is not freely available for scientific study because the raw data have not been made accessible to the public. Our reflectance model and the calibration procedure reported here are freely available to the public, and the raw data and calibration filter tool can also be downloaded from the WEB site of one of the authors; “Moon Base Osaka (<http://astrosis.ess.sci.osaka-u.ac.jp/MBO.html>)”.

## 2. Method

To gain lunar absolute radiance and reflectance, we acquired multi-band images of the lunar surface and those of some standard stars using a hyper-spectral telescope located on the peak of Mt. Haleakala (Hawaii, USA). Our hyper-spectral telescope system consists of a telescope, a cooling CCD camera, a liquid-crystal tunable filter (LCTF), and a notebook computer for importing images and tuning the wavelength of LCTF. The telescope is a Vixen GP-ED80SM with an ED (extra-low dispersion glass) apochromatic objective refractor. The effective aperture is 80 mm and the focal length is 720 mm. The CCD camera is an Apogee U260 with a CCD Kodak KAF-0261E. The pixels are arranged in a 512 (H)  $\times$  512 (V) array, and the pixel size is 20  $\mu\text{m}$ . The LCTF, model VeriSpec™ NIR-07 (Cambridge Research Instrumentation), is placed between the telescope and the CCD camera. The LCTF is essentially a multistage Lyot-Ohman type polarization interference filter with an added liquid-crystal waveplate in each stage providing an electronically controllable variable retardance (Gat, 2003). The controller of the LCTF has an USB peripheral connector for direct interface to the notebook computer's USB. The filter functions like a high-quality interference

Table 1. Observation of standard stars.

Date	Name of standard star	Number of measurements				
		650 nm	750 nm	900 nm	950 nm	1000 nm
18 Aug. 2005	Nunki ( $\sigma$ Sagittarii)	15	15	15	15	15
20 Aug. 2005	Fomalhaut ( $\alpha$ Piscis Austrini)	25	25	25	25	25
15 Dec. 2005	Elnath ( $\beta$ Tauri)	40	40	40	40	21

filter, but the wavelength of light it transmits is electronically tunable and allows for the rapid, vibrationless selection of any wavelength in the near-infrared (NIR) region. The filter covers the wavelength range of 650–1100 nm with the full-width half-maximum (FWHM) of 7 nm. The telescope is set on the equatorial mount with a tripod. It can be aimed at a celestial object and guided by an electric motor drive controlled by an external telescope computer, Vixen Skysensor 2000PC, to follow the object across the sky. The location of the observation was Science City at the peak of Mt. Haleakala, Maui, Hawaii, USA. For the calculation of lunar and stellar position, we used a longitude of  $156^{\circ}15'23''\text{W}$ , latitude of  $20^{\circ}42'27''\text{N}$ , and altitude of 3040 m as the location of observation. The dates of the observations were August 15–26, 2005 and December 12–18, 2005. Among all data, the data of 18 and 20 August and 15 December were selected because atmospheric conditions were relatively stable during these observational times, and the indispensable data sets that included one standard star situated close to the Moon, Vega, and the Moon were successfully obtained. The images of some standard stars, Vega, and the Moon at five bands—650, 750, 900, 950, and 1000 nm—were obtained. Four bands among these have the same wavelength as the UV/VIS sensor of Clementine and the MI sensor of SELENE. The optical depth of the day was obtained by observing Nunki ( $\sigma$  Sagittarii), Fomalhaut ( $\alpha$  Piscis Austrini), and Elnath ( $\beta$  Tauri) as a standard star (Table 1).

### 3. Data Analysis

Dark-field and flat-field corrections were applied to each image obtained by CCD. Sky flats were used as the flat field. Atmospheric correction is indispensable to gain lunar extra-atmospheric irradiance, as aerosol, nitrogen, oxygen, and atmospheric water vapor scatter and absorb the lunar light. Atmospheric correction removes these atmospheric effects. The observed intensity ( $DN_{\text{obs}}$ ) of an astronomical object is expressed by the Lambert-Beer law as

$$\ln DN_{\text{obs}} = -\tau\alpha + \ln DN_0$$

where  $DN_0$  is the extra-atmospheric intensity,  $\tau$  is the optical depth of the atmosphere, and  $\alpha$  is the optical air-mass factor expressed by elevation angle of the object;  $\theta$  as  $\alpha = 1/\sin\theta$ .  $\ln DN_{\text{obs}}$  is linearly related to  $\alpha$  as long as  $\tau$  is constant. Figure 1 is an example of a Langley plot (Shiobara *et al.*, 1996; Langley, 1881) of some  $DN_{\text{obs}}$  sets of one star obtained at the different elevation angles.  $DN_0$  is determined by extrapolating the best-fit line on the Langley plots to zero-airmass assuming that  $\tau$  is constant during the observation. The  $\tau$  of the day was calculated from the images of standard stars, and then using the same  $\tau$ , we cal-

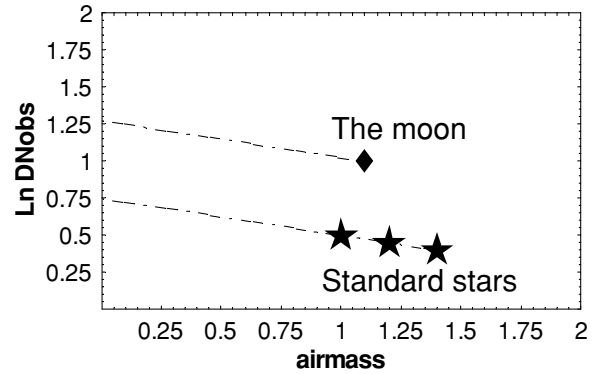


Fig. 1. An example of a Langley plot. Three observations of a standard star and one observation of the Moon are plotted. Dotted lines indicate estimated signal intensities for each airmass.

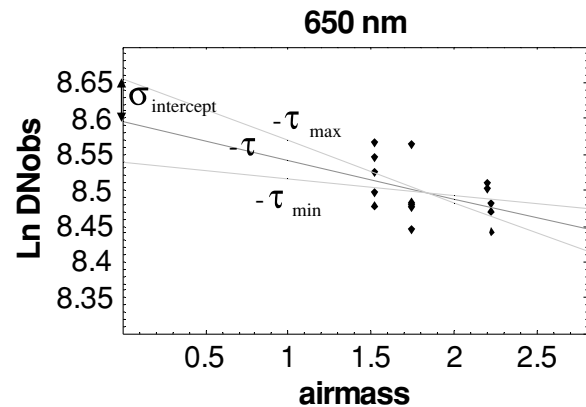


Fig. 2. A diagram showing how to define the range of the optical depth of the atmosphere,  $\tau$ . Solid diamonds indicate the integrated intensities of the standard star Nunki ( $\sigma$  Sagittarii) at 650 nm observed on 18 August 2005.

culated the extra-atmospheric intensity of the Moon from the observed intensity of the Moon. An example of how to estimate  $\tau$  and its error is provided in the calculations shown in Fig. 2. The integrated intensities of the standard star Nunki ( $\sigma$  Sagittarii) observed on 18 August 2005 are plotted as solid diamonds on the Langley plot (Fig. 2). The value of  $\tau$  is defined as the sign-reversed slope of the best-fit line obtained by linear regression of all data in the plot. The error of  $\tau$  ( $\sigma_\tau$ ) is determined from

$$\sigma_y = \sqrt{\frac{1}{N-2} \sum (y_i - (-\tau\alpha_i + \ln DN_0))^2}$$

$$\sigma_\tau = \sigma_y \sqrt{\frac{\sum \alpha_i^2}{N \sum \alpha_i^2 - (\sum \alpha_i)^2}}$$

Table 2. Extra-atmospheric irradiance of Vega and the Sun at the Earth/the Moon used for this study. Gaussian transmissivity filter coefficient with 7-nm FWHM has been applied.

	650 nm	750 nm	900 nm	950 nm	1000 nm
$I_{\text{Vega-Earth}} (\times 10^{-8} \text{ W/m}^2/\mu\text{m})$	2.080	1.373	0.7941	0.7194	0.6079
$I_{\text{Sun-Moon}} (\times 10^3 \text{ W/m}^2/\mu\text{m})$	1.548	1.280	0.9203	0.8210	0.7323
$I_{\text{Sun-Earth}}^{*1} (\times 10^3 \text{ W/m}^2/\mu\text{m})$	1.59	1.27	0.920	0.833	0.746
$I_{\text{Sun-Earth}}^{*2} (\times 10^3 \text{ W/m}^2/\mu\text{m})$	1.59	1.27	0.914	0.779	0.744

\*<sup>1</sup>reference data based on Kurucz (1995). \*<sup>2</sup>reference data based on Wehrli (1985).

where  $N$  is the number of data, and  $y_i$  is  $\ln DN_{\text{obs}}$  at airmass  $\alpha_i$ . Two light-gray lines show  $\tau$  maximum,  $\tau_{\text{max}} = \tau + \sigma_\tau$ , and  $\tau$  minimum,  $\tau_{\text{min}} = \tau - \sigma_\tau$ , respectively. The error of  $\ln DN_0$ , the  $\sigma_{\text{Intercept}}$ , is determined from

$$\sigma_{\text{Intercept}} = \sigma_y \sqrt{\frac{N}{N \sum \alpha_i^2 - (\sum \alpha_i)^2}}.$$

The extra-atmospheric irradiance of the Moon at the Earth,  $I_{\text{Moon-Earth}}$ , is calculated by the following equation.

$$I_{\text{Moon-Earth}} = I_{\text{Vega-Earth}} \times DN_{\text{Moon}}/DN_{\text{Vega}}$$

where:  $I_{\text{Vega-Earth}}$  is the extra-atmospheric irradiance of Vega at the Earth, derived from the spectral irradiance of Vega characterized by Bohlin and Gilliland (2004). The Gaussian transmissivity filter coefficient of our LCTF with 7-nm FWHM has been multiplied by the Vega irradiance spectrum.  $DN_{\text{Vega}}$  and  $DN_{\text{Moon}}$  is the extra-atmospheric intensity per second of Vega and the Moon calculated from observations using the Lambert-Beer law. The radiance of the Moon,  $B_{\text{Moon}}$ , is converted from  $I_{\text{Moon-Earth}}$  as follows.

$$B_{\text{Moon}} = I_{\text{Moon-Earth}} \times \pi \times d_{\text{Moon-Earth}}^2 / A_{\text{pixel}}$$

where  $A_{\text{pixel}}$  is the area of lunar surface corresponding to one pixel on the lunar image calculated by (diameter of the Moon (3476 km)/diameter of the Moon image (pixels))<sup>2</sup>, and  $d_{\text{Moon-Earth}}$  is the distance between the Moon and the Earth. Reflectance of the Moon,  $R_{\text{Moon}}$ , is obtained by  $R_{\text{Moon}} = B_{\text{Moon}}/I_{\text{Sun-Moon}} \times 100$ .  $I_{\text{Sun-Moon}}$  is the solar spectral irradiance at the Moon. To estimate  $I_{\text{Sun-Moon}}$ , the radiance of the Sun,  $B_{\text{Sun}}$ , is derived from Planck's law as follows.

$$B_{\text{Sun}} = \frac{2hc^2\pi}{\lambda^5 \left( \exp\left(\frac{hc}{\lambda kT}\right) - 1 \right)}$$

where  $h$  is Planck's constant,  $c$  is the speed of light,  $\lambda$  is the wavelength,  $k$  is the Boltzmann's constant, and  $T$  is the temperature of the black body. A temperature of 5777 K is applied as  $T$  for the solar spectrum. Solar irradiance at the Moon is calculated as follows:

$$I_{\text{Sun-Moon}} = B_{\text{Sun}} \times G \times (d_{\text{Sun-Earth}}/R)^2$$

where  $G$  is the Gaussian transmissivity filter coefficient of our LCTF with 7-nm FWHM,  $d_{\text{Sun-Earth}}$  is the distance between the Sun and the Earth, and  $R$  is the radius of the Sun. The  $I_{\text{Vega-Moon}}$  and  $I_{\text{Sun-Moon}}$  used for this study are listed in Table 2 with two reference data of extraterrestrial

Table 3. Lunar data for the image at 950 nm on 18 August 2005.

UTC	2005-08-18 9:09
HST (Hawaii Standard Time)	2005-08-18 23:09
JST (Japan Standard Time)	2005-08-19 18:09
Sub-Earth_longitude	0.819°
Sub-Earth_latitude	6.039°
Sub-solar_latitude	1.161°
Sub-solar co-longitude	84.114°
Illumination	0.9962
Elevation angle	47.2°
Distance Earth-Moon	$3.574 \times 10^5$ km
Distance Earth-Sun	1.012 AU
Exposure time	200 ms
Radius of the lunar image	177 pixels

irradiance of the Sun;  $I_{\text{Sun-Earth}}$  is based on Kurucz (1995) and Wehrli (1985). Even if we use the reference  $I_{\text{Sun-Earth}}$  instead of  $I_{\text{Sun-Moon}}$  derived from Planck's law, the result will not change a lot.

The reflectance of the Moon should be normalized to match the photometric geometry of the lunar samples ( $i = 30^\circ$ ,  $e = 0^\circ$ ) measured at the laboratory at Brown University (RELAB) (McEwen *et al.*, 1998). Therefore, the irradiance of the Sun on the Moon is multiplied by  $\cos 30^\circ$  to gain effective irradiance:  $I'_{\text{Sun-Moon}} = I_{\text{Sun-Moon}} \times \cos 30^\circ$ . The photometric correction removes the effects of the geometry of the observing system owing to topography, phase, and libration on apparent reflectance. In this study the Clementine photometric function (Pieters *et al.*, 1991) was applied as follows.

$$f_n = 0.988 - 2.101 \times p/100.0 + 2.527 \times p^2/10^4 - 1.530 \times p^3/10^6 + 3.367 \times p^4/10^9$$

$$C_{\text{photo}} = 0.25366/f_n / \cos(i) \times (\cos(e) + \cos(i))$$

where  $p$  is the phase angle,  $i$  is the incident angle, and  $e$  is the emission angle. When the phase angle was less than  $5^\circ$ , we applied Yokota's function (Yokota *et al.*, 1999) as follows.

$$C_{\text{photo}} = 0.4641016 / \cos(i) \times (\cos(e) + \cos(i)) / (-0.12 \times p + 2.2)$$

Each pixel of the lunar image has a different  $i$  and  $e$  value, therefore  $C_{\text{photo}}$  is also different. A software "LunaFilter" that makes a filter image from the lunar data, such as sub-Earth longitude, sub-Earth latitude, sub-solar latitude, sub-solar co-longitude, illumination, elevation angle, distance between the Earth and the Moon, distance between the Earth and the Sun, exposure time, and radius of lunar

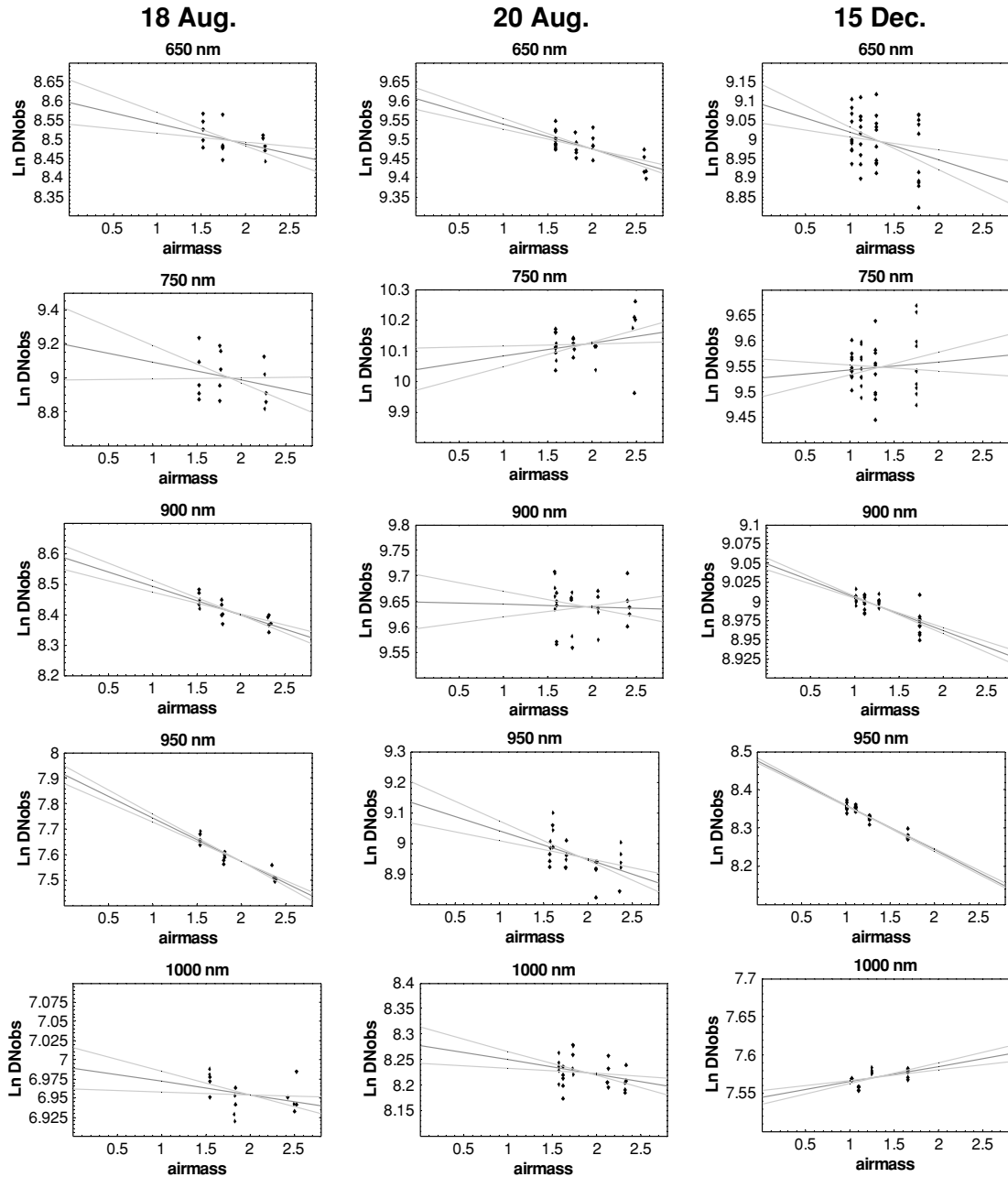


Fig. 3. The Langley plots of the standard stars at five bands on 18 and 20 August 2005 and 15 December 2005. The center lines are the best-fit lines obtained by linear-regression of all data sets at each band. Their gradient defines  $-\tau$ . The lines that define  $\tau_{\max}$  and  $\tau_{\min}$  are also shown.

image (Table 3), has been developed and provided at the WEB site “Moon Base Osaka”. Each pixel of the filter image has the value that converts the lunar image to the reflectance image. Each pixel on the filter image is calculated by the following equation.

$$C_{\text{filter}} = C_{\text{photo}} \times I_{\text{Vega-Earth}} / DN_{\text{Vega}} \times d_{\text{Moon-Earth}}^2 / A_{\text{pixel}} \times M / E / I'_{\text{Sun-Moon}} \times \pi \times 100 / \exp(\tau(1/\sin(\theta)))$$

where  $C_{\text{filter}}$  is the filter coefficient (pixel value of the filter image),  $E$  is the exposure time for the Moon image,  $\theta$  is the altitude of the Moon, and  $M$  is the coefficient used to expand the reflectance value to fit the scale of a 16 bit-integer. The resultant image has the value  $DN_{\text{Moon}} \times C_{\text{filter}} = R_{\text{Moon}} \times M$ .

#### 4. Results

Five to ten images of the standard star were obtained three to five times each night. The optical depth of the atmosphere,  $\tau$ , and its error,  $\sigma_{\tau}$ , were estimated each night from the data of the standard star. The selected standard stars and number of measurements are shown in Table 1. The atmospheric conditions during each observation were estimated using the Langley plot. The plot of the natural log of the integrated intensity of the standard star at five bands versus the airmass on 18 and 20 August 2005 and 15 December 2005 are shown in Fig. 3. The estimated optical depth of the atmosphere,  $\tau$ , its error,  $\sigma_{\tau}$ , and the R-square for the best-fit line are shown in Table 3. In an ideal case,  $\tau$  has a positive value. The fact that some  $\tau$  at 750 and 1000 nm have a negative value indicates that the

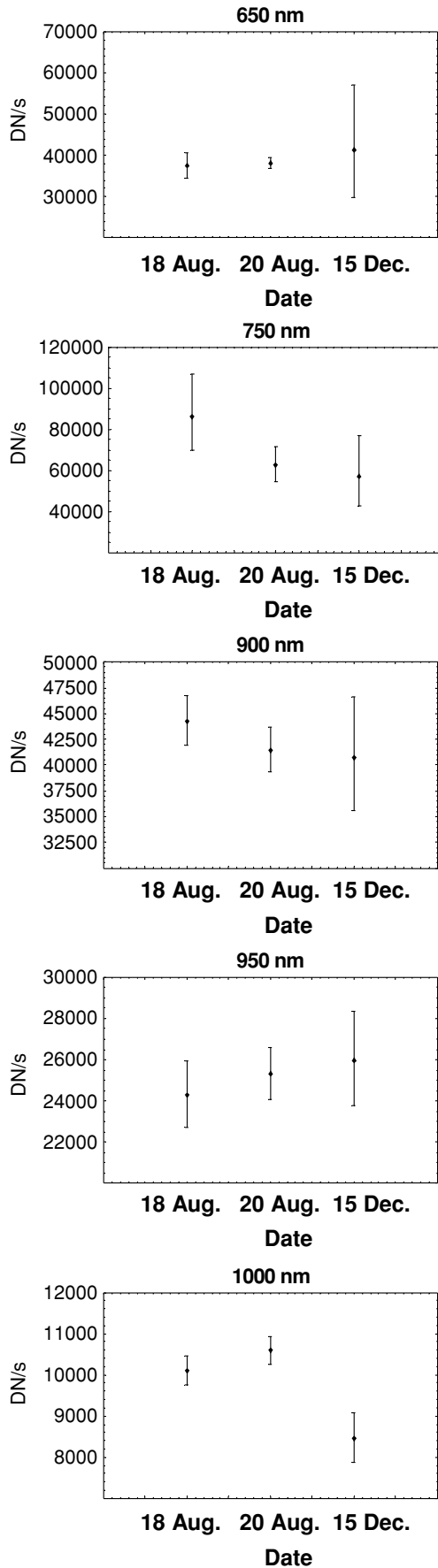


Fig. 4. Estimation of the extra-atmospheric intensities of Vega and their error range.

atmospheric absorptions at 750 and 1000 nm are unstable, probably due to water vapor.

In this study, Vega was used for the calibration standard for our telescope. The extra-atmospheric intensity ( $DN$ ) of Vega was calculated using the optical depth of the atmosphere,  $\tau$ , and Vega observations, and is shown in Fig. 4. The range of  $DN_0$  of Vega was defined by the range of  $\tau$  ( $\tau_{\min} \sim \tau_{\max}$ ) and the range of  $\pm 1\sigma$  of  $\ln DN_{\text{obs}}$  using the Lambert-Beer law. The data in December have a wide error range because the elevation angle of Vega was much lower than on 18 and 20 August. The  $DN$ s of Vega show some variation, mostly owing to atmospheric conditions. If we assume that the  $DN$  of Vega should be the same value within the same wavelength, Fig. 4 indicates that the data of 650, 900, and 950 nm were relatively insensitive to atmospheric conditions, while those of 750 and 1000 nm were sensitive to atmospheric conditions. This tendency is consistent with the tendency deduced from the negative value of the optical depth (Fig. 3).

The Langley-plot (Fig. 3) and R-square (Table 4) indicate that the atmospheric conditions on 18 August were the best among these three nights. The reflectance of the Moon at the five bands on 18 August was calculated, and the reflectance images are freely available to the public at the WEB site “Moon Base Osaka”. Among the data obtained on 18 August, the data at 950 nm appears to be the most reliable because their R-square has a high value. Therefore, we will examine the lunar reflectance image on 18 August at 950 nm in more detail. The reflectance image and its histogram are shown in Fig. 5. The peak reflectance for the mare area is 7.2~7.4% and that for highland area is 12.8~13.0%. Our lunar reflectance data were compared with Clementine UV/VIS data. Figure 6(a) is a part of our lunar reflectance image at 950 nm. A profile of reflectance (Fig. 6 (b)) was derived along the line (Lat: 43.3°S, Long: 20.0°W)-(Lat: 43.3°S, Long: 11.1°W)-(Lat: 43.3°S, Long: 0.0°W). This line cuts across Tycho. On the other hand, Fig. 6(c) is the 950-nm reflectance image from the Clementine UV/VIS mosaic. Its profile of reflectance (Fig. 6(c)) is also derived along the line connecting the same three points. The spatial resolution and the map-projection are clearly different between these two profiles, and two lines therefore cannot perfectly coincide with each other. However, given the expectation that two lines cover almost the same area, it is obvious that the UV/VIS reflectance data are much higher than our data. The average reflectance on the line of our data is 15.2% and that of UV/VIS is 25.6%. The correction factor would be approximately 0.59. Although it is known that increasing the spatial resolution results in unexpectedly high reflectance values, it would not affect the average reflectance this much.

## 5. Discussion

Let us now estimate the error of our lunar reflectance. Among the factors expected to cause an error, the error of optical depth,  $\tau$ , and observed intensity,  $DN_{\text{obs}}$ , would be extraordinary large. Therefore, we present here the error caused by these factors as a tentative estimation. The error of extraterrestrial irradiance of the Sun,  $I_{\text{Sun-Earth}}$ , may be large, but it is difficult to estimate. We entrust the

Table 4. The estimated optical depth of the atmosphere with error and coefficient of determination.

Date		650 nm	750 nm	900 nm	950 nm	1000 nm
18 Aug. 2005	$\tau$	0.05420	0.1066	0.09303	0.1702	0.01739
	$\sigma_\tau$	0.03194	0.1116	0.02084	0.0184	0.01361
	$R^2$	0.18	0.07	0.61	0.87	0.11
20 Aug. 2005	$\tau$	0.06576	-0.04380	0.005281	0.09398	0.02874
	$\sigma_\tau$	0.01446	0.03595	0.027787	0.03531	0.01851
	$R^2$	0.47	0.06	0.00	0.24	0.09
15 Dec. 2005	$\tau$	0.07249	-0.01554	0.04371	0.1164	-0.02032
	$\sigma_\tau$	0.03783	0.027442	0.00606	0.0050	0.00697
	$R^2$	0.09	0.01	0.58	0.94	0.31

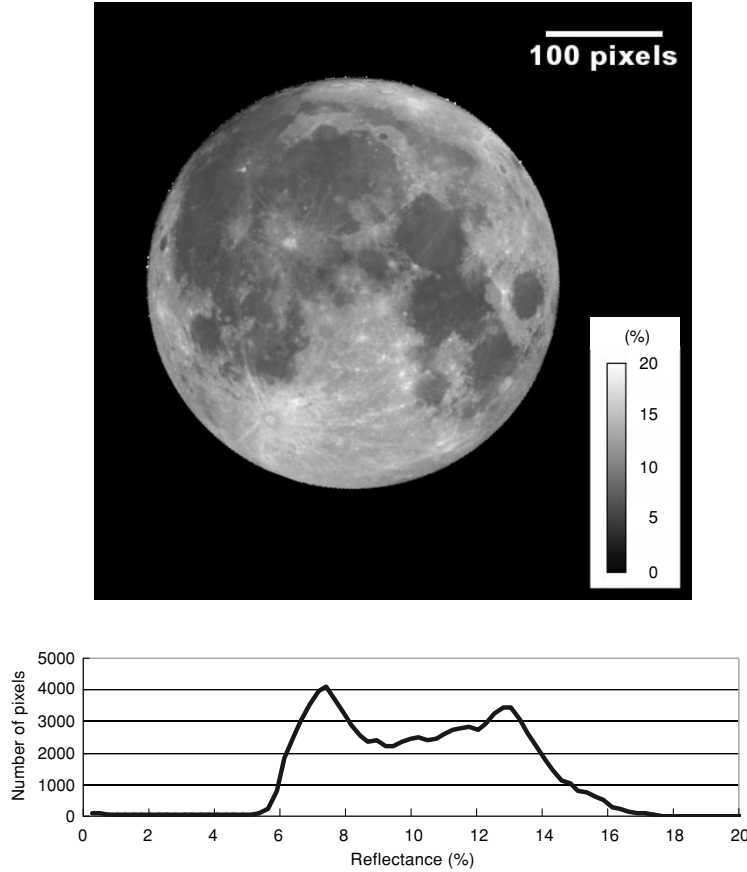


Fig. 5. The reflectance image of the Moon at 950 nm and its histogram.

selection of solar irradiance model and the addition of its error to the users of our reflectance data. The photometric function can also change the reflectance, and a rational estimation of its error is impossible. Therefore, we make our raw data freely available to the public and users can change the photometric function as they like. The range of  $DN_0$  of Vega was defined by the maximum and minimum value of  $DN_0$  as calculated by the range of  $\tau$  ( $\tau_{\min} \sim \tau_{\max}$ ) and the range of  $\pm 1\sigma$  of  $\ln DN_{\text{obs}}$  using the Lambert-Beer law (Fig. 4). The fractional uncertainty of Vega,  $\delta_{\text{Vega}}$ , was determined from  $\delta_{\text{Vega}}(+)=|DN_0^{\text{Vega-Max}} - DN_0^{\text{Vega-best}}|/DN_0^{\text{Vega-best}} \times 100$  (%), and  $\delta_{\text{Vega}}(-)=|DN_0^{\text{Vega-Min}} - DN_0^{\text{Vega-best}}|/DN_0^{\text{Vega-best}} \times 100$  (%) (Table 5). On the other hand, it is difficult to estimate  $\sigma$  of  $\ln DN_{\text{obs}}$  of the Moon because of subpixel displacement of the lunar images. The integrated intensity of the

lunar hemi-sphere did not change over  $\pm 0.1\%$ ; therefore, so long as the reflectance value is sampled not from a single pixel but from the appropriate area, the effect of scintillation would be negligible.

The range of  $DN_0$  of the Moon was defined by the maximum and minimum value of  $DN_0^{\text{Full-Scale}}$  calculated only by the range of  $\tau$  ( $\tau_{\min} \sim \tau_{\max}$ ) using the Lambert-Beer law (Fig. 4). The intensity of the brightest pixel within a lunar image was applied as  $DN_0^{\text{Moon-FullScale}}$ . The fractional uncertainty of the Moon,  $\delta_{\text{Moon}}$ , was determined from  $\delta_{\text{Moon}}(+)=|DN_0^{\text{Moon-Max}} - DN_0^{\text{Moon-FullScale}}|/DN_0^{\text{Moon-FullScale}} \times 100$  (%), and  $\delta_{\text{Moon}}(-)=|DN_0^{\text{Moon-Min}} - DN_0^{\text{Moon-FullScale}}|/DN_0^{\text{Moon-FullScale}} \times 100$  (%) (Table 5). The lunar reflectance is proportional to  $DN_0^{\text{Moon}}$  and  $1/DN_0^{\text{Vega}}$ ; therefore, the fractional uncertainty of the lunar reflectance,  $\delta_{\text{Reflectance}}$ , is determined from  $\delta_{\text{Reflectance}} = \delta_{\text{Moon}} + \delta_{\text{Vega}}$

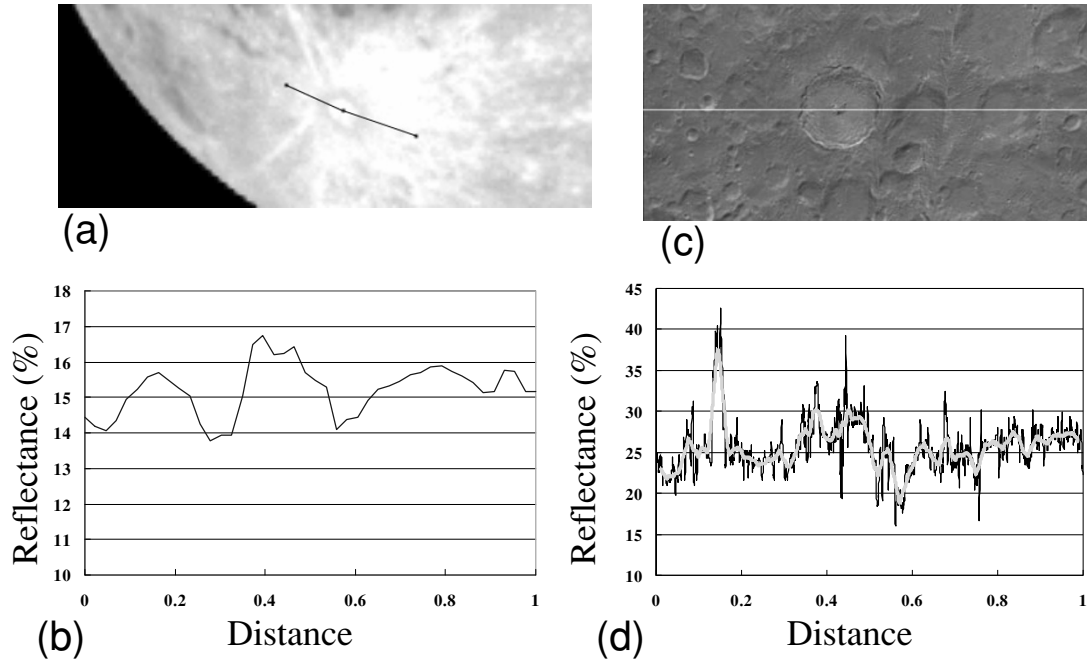


Fig. 6. Comparison between our reflectance image (a) and the Clementine UV/VIS image (c) at 950 nm around Tycho. Reflectance profiles (b) and (d) are derived from the line defined by three points: (Lat: 43.3°S, Long: 20.0°W)-(Lat: 43.3°S, Long: 11.1°W)-(Lat: 43.3°S, Long: 0.0°W) on (a) and (c), respectively. A thick line on (d) is filtered using a 10-km moving average.

Table 5. A tentative estimation of fractional uncertainty of our results (%).

		650 nm	750 nm	900 nm	950 nm	1000 nm
$DN_0$ Vega	$\delta(+)$	8.31	23.6	5.69	6.81	3.48
	$\delta(-)$	7.67	19.1	5.38	6.38	3.36
$DN_0$ Moon	$\delta(+)$	4.54	16.7	2.90	2.54	1.87
	$\delta(-)$	4.34	14.3	2.82	2.48	1.83
Lunar reflectance	$\delta(+)$	12.9	40.3	8.59	9.35	5.35
	$\delta(-)$	12.0	33.4	8.20	8.86	5.19

(Table 5).

The absolute spectral calibration for Clementine reflectance data was carried out using the laboratory measurement data of lunar soil 62231 on the assumption that the reflectance spectrum of Apollo soil 62231 is representative of the calibration target area named Apollo 16 West. The discordance between Clementine data and ground-based observations (Hillier *et al.*, 1999; Shkuratov *et al.*, 2001; this study) indicates that this assumption should be wrong. Even if a standard soil was sampled directly from the lunar surface, the spectrum of the soil is not always representative of the area's spectra because of the heterogeneity of the lunar surface. Furthermore, 62231 had not been sampled within Apollo 16 West. The reflectance could be affected by the conditions of the measurement, such as the compaction state of the soil (M. Ohtake, personal communication). Given the estimated error (Table 5), the correction factor of the Clementine UV/VIS camera would be  $0.59 \pm 0.06$  at 950 nm. This value is very close to the value 0.532 presented by Hillier *et al.* (1999). When determining the absolute reflectance of the lunar surface from the lunar image obtained by the sensor of spacecrafts, ground-based observation data is more reliable as the calibration standard than laboratory measurement data of lunar soil, even though

the atmosphere disturbs the ground-based observation. The accuracy of ground-based data would be improved by the further accumulation of observation data. The advantage of ground-based observations is that we can compare the obtained data with those of other scientists. Therefore, we make our data freely available to the public.

## 6. Conclusion

- The lunar reflectance images at 650, 750, 900, 950, and 1000 nm were made from the lunar images obtained with a hyper-spectral telescope located at the peak of Mt. Haleakala (Hawaii, USA).
- On the basis of a 3-day comparison of observations, the optical depths at 750 and 1000 nm appeared to be unstable, probably due to water vapor, and those of 650, 900, and 950 nm were relatively stable.
- The reflectance value of Clementine UV/VIS is much brighter than our data. The correction factor would be  $0.59 \pm 0.06$  at 950 nm. This value is close to the value 0.532 presented by Hillier *et al.* (1999).

The lunar reflectance images, the software tools, and the raw data are freely available to the public at the web site “Moon Base Osaka”.

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